Abstract

ISSN 1178-9905 (print edition) ZOOSYMPOSIA ISSN 1178-9913 (online edition)

https://doi.org/10.11646/zoosymposia.22.1.87

Mechanical devices for off-host tick surveillance*

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*In: Zhang, Z.-Q., Fan, Q.-H., Heath, A.C.G. & Minor, M.A. (Eds) (2022) Acarological Frontiers: Proceedings of the XVI International Congress of Acarology (1–5 Dec. 2022, Auckland, New Zealand). Magnolia Press, Auckland, 328 pp.

Standard methods for collecting off-host ticks—flags, drags and leggings—expose the investigator to hazards and are typically less efficient for detection of larvae compared to adults. The potential for using mechanical devices such as vacuums and robots was explored. A vacuum device made by reversing the tube on a leaf blower was tested in a pasture known to be infested with cattle fever ticks. For comparison the same pasture was sampled using leggings and by scratch inspection of the infested cattle. Detection of larvae was markedly episodic by both methods reflecting life cycle periodicity. There was a lag of about 3 weeks between detection of larvae in the pasture and adult ticks on the cattle. Over a year of sampling the vacuum collected greater numbers of larval ticks, but the leggings detected clusters of ticks with somewhat greater frequency.

An electric motor driven robot vehicle operated by remote control was fitted with hinged flags and tested in different pasture habitats encountered in south Texas. Larval ticks were found clinging to the flags after runs through an infested pasture. However, while the robot was able to navigate around obstacles and through thorny brush it depended on the operator having the rover in sight. The simultaneous use of the rover and an overhead drone mounted camera was useful only when visibility was not blocked by tree crowns. Although the rover had four-wheel drive it would still high center on bunch grass and woody shrubs. Successful operation in more open habitat was restricted to following trails.

Keywords: tick-vac, tick-bot, off-host tick surveillance, sampling, tick larvae, drones